Topics and Equations for AP Physics C: Electricity & Magnetism

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You are permitted use of a scientific calculator and the College Board's AP Physics equation sheet for the ENTIRE exam (see www.collegeboard.org/ap/calculators for a list of acceptable calculators). The reason for this is explained in the AP Physics Course Description:

The purpose of allowing calculators and equation sheets to be used in both sections of the exam is to place greater emphasis on the understanding and application of fundamental physical principles and concepts. For solving problems and writing essays, a sophisticated scientific or graphing calculator, or the availability of equations, is no substitute for a thorough grasp of the physics involved. The availability of these equations to all students means that in the scoring of the exam, little or no credit will be awarded for simply writing down equations or for answers unsupported by explanations or logical development.

The AP Physics equation sheet provides a list of fundamental equations from which all others may be derived. The following list, adapted from Tipler & Mosca's <u>Physics for Scientists and Engineers, Fourth</u> <u>Edition</u>, describes the topics and *all* of the equations with which you should be familiar before you take the AP Physics C: Electricity and Magnetism Exam. **The fundamental equations provided by the College Board are indicated with an asterisk * on the following pages.**

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ELECTRIC FIELD: DISCRETE CHARGE DISTRIBUTIONS

| ELECTRIC FIELD: DISCRETE C | |
|------------------------------|---|
| | 1. Quantization and conservation are fundamental properties of electric charge. |
| | 2. Coulomb's law is the fundamental law of interaction |
| | between charges at rest. |
| | 3. The electric field describes the condition in space set up |
| | by a charge distribution. |
| ТОРІС | RELEVANT EQUATIONS AND REMARKS |
| 1. Charge | There are two kinds of charge, positive and negative. |
| | Charges of like sign repel, those of opposite sign attract. |
| Quantization | Charge is quantized—it always occurs in integer multiples |
| | of the fundamental charge unit <i>e</i> . The charge of the |
| | electron is $-e$ and that of the proton is $+e$. |
| Magnitude | $e = 1.60 \times 10^{-19} \text{ C}$ |
| Conservation | Charge is conserved. When charged particles are created |
| | or annihilated, the total amount of charge carried by the |
| | created or annihilated particles is zero. |
| 2. Conductors and Insulators | In metals, about one electron per atom is delocalized (free |
| | to move about the entire material). In insulators, all the |
| | electrons are bound to nearby atoms. |
| Ground | A very large conductor (such as Earth) that can supply or |
| | absorb a virtually unlimited amount of charge is called a |
| | ground. |
| 3. * Coulomb's Law | The force exerted by point charge q_1 on point charge q_2 a |
| | distance r_{12} away is given by |
| | $\vec{F}_{12} = \frac{kq_1q_2}{r_{12}^2}\hat{r}_{12}$ |
| Coulomb's constant | $k = 8.99 \times 10^{-19} \text{ N} \cdot \text{m}^2/\text{C}^2 \approx 9.00 \times 10^{-19} \text{ N} \cdot \text{m}^2/\text{C}^2$ |

ELECTRIC FIELD: DISCRETE CHARGE DISTRIBUTIONS

| ТОРІС | RELEVANT EQUATIONS AND REMARKS |
|----------------------------------|--|
| 4. * Electric Field | The electric field due to a system of charges at a point is |
| | defined as the net force \vec{F} exerted by those charges on a |
| | very small positive test charge q_0 divided by q_0 : |
| | $\vec{E} \equiv rac{\vec{F}}{q_0}$ |
| Due to a point charge | $\vec{E} = \frac{kQ}{r^2}\hat{r}$ |
| Due to a system of point charges | The electric field at a point due to several charges is the |
| | vector sum of the fields at that point due to the individual |
| | charges: |
| | $\vec{E}_{net} = \sum_{i=1}^{n} \vec{E}_{i}$ |
| 5 Electric Field Lines | The electric field can be represented by electric field lines |
| | that emanate from positive charges and terminate on |
| | negative charges (the direction of the electric field is |
| | defined to be the direction a small positive charge would |
| | move if placed in the field). The strength of the electric |
| | field is indicated by the density of the electric field lines. |

ELECTRIC FIELD: CONTINUOUS CHARGE DISTRIBUTIONS

TOPIC

- 1. Gauss's law is a fundamental law of physics that is equivalent to Coulomb's law for static charges.
- 2. For highly symmetric charge distributions, Gauss's law can be used to calculate the electric field.

RELEVANT EQUATIONS AND REMARKS

| 1. Electric Field for a Continuous | $\vec{E} = \int d\vec{E} = \int \frac{k dq}{r^2} \hat{r}$ |
|---------------------------------------|--|
| Charge Distribution | where |
| | $dq = \rho dV$ for a charge distributed throughout a volume |
| | $dq = \sigma dA$ for a charge distributed on a surface |
| | $dq = \lambda dL$ for a charge distributed along a line |
| 2. Electric Flux | $\Phi_E = EA\cos\theta = \int \vec{E} \cdot d\vec{A}$ |
| 3. * Gauss's Law | $\Phi_{E,net} = \oint_{surface} \vec{E} \cdot d\vec{A} = \frac{Q_{inside}}{\epsilon_0}$ |
| | The net electric flux through a closed surface equals the |
| | net charge within the surface divided by ϵ_0 . |
| Permittivity of free space | $\epsilon_0 = 8.85 \times 10^{-12} \text{ C}^2/\text{N} \cdot \text{m}^2$ |
| Coulomb's constant | $k = \frac{1}{4\pi\epsilon_0}$ |
| 4. Charge on a Conductor | In electrostatic equilibrium, the charge density is zero throughout the material of the conductor. All excess or deficit charge resides on the outer surfaces of the |
| <u>→</u> | conductor. |
| 5. \vec{E} just Outside a Conductor | The resultant electric field just outside the surface of a |
| | conductor is normal to the surface and has the magnitude $E_n = \frac{O}{\epsilon_0}$ |
| | where σ is the local surface charge density on the |
| | conductor. |

- 1. Electric potential at a location, which is defined as the electric potential energy per unit charge that a test charge would have at that location, is an important derived physical concept that is related to the electric field.
- 2. Because potential is a scalar quantity, it is often easier to calculate than the electric field. Once *V* is known,
 - \vec{E} can be calculated from V.

TOPIC

1. Potential Difference

RELEVANT EQUATIONS AND REMARKS

The potential difference $V_b - V_a$ is defined as the negative of the work per unit charge done by the electric field on a test charge as it moves from point *a* to point *b*:

| | $\Delta V \equiv V_b - V_a = \frac{\Delta U}{q_0} = -\int_a^b \vec{E} \cdot d\vec{s}$ |
|--|---|
| Potential from infinitesimal | $dV = -\vec{E} \cdot d\vec{s}$ |
| displacements | |
| 2. Electric Potential | |
| Potential due to a point charge | $V = \frac{kq}{r} = \frac{1}{4\pi\epsilon_0} \frac{q}{r} (V=0 \text{ if } r=\infty)$ |
| * Potential due to a system of charges | $V = k \sum_{i=1}^{n} \frac{q_i}{r_i}$ |
| Potential due to a continuous charge | $V = k \int \frac{dq}{r}$ |
| distribution | where dq is an increment of charge and r is the distance |
| | from the increment to the field point. This expression can |
| | be used only if the charge distribution is contained in a |
| | finite volume so that the potential can be chosen to be zero |
| | at infinity. |

ELECTRIC POTENTIAL

| TOPIC | RELEVANT EQUATIONS AND REMARKS |
|---|---|
| Continuity of electric potential | The potential function V is continuous everywhere in |
| | space. |
| 3. Computing the Electric Field | The electric field points in the direction of the most rapid |
| from the Potential | decrease in the potential. |
| Gradient | A vector that points in the direction of the greatest rate of |
| | change in a scalar function and that has a magnitude equal |
| | to the derivative of that function, with respect to the |
| | distance in that direction, is called the gradient of the |
| | function. \vec{E} is the negative gradient of <i>V</i> . |
| Potential as a function of x alone | $E_x = -\frac{d}{dx}V(x)$ |
| * Potential as a function of <i>r</i> alone | $E_r = -\frac{d}{dr}V(r)$ |
| 4. General Relation between \vec{E} and V | $\vec{E} = -\vec{\nabla}V = -\left(\frac{\partial v}{\partial x}\hat{i} + \frac{\partial v}{\partial y}\hat{j} + \frac{\partial v}{\partial z}\hat{k}\right)$ |
| 5. Units | |
| V and ΔV | The SI unit of potential and potential difference is the volt: |
| | 1 V = 1 J/C |
| Electric field | 1 N/C = 1 V/m |
| Electron volt | The electron volt (eV) is the change in potential energy of |
| | a particle of charge <i>e</i> as it moves from <i>a</i> to <i>b</i> where |
| | $V_b - V_a = 1$ volt: |
| | $1 \text{ eV} = 1.60 \times 10^{-19} \text{ C} \cdot \text{V} = 1.60 \times 10^{-19} \text{ J}$ |
| 6. * Potential Energy of Two Charges | $U = q_0 V = \frac{k q_0 q}{r} (U = 0 \text{ if } r = \infty)$ |

ELECTRIC POTENTIAL

| TOPIC | RELEVANT EQUATIONS AND REMARKS |
|---------------------------------------|--|
| 7. Charge on a Nonspherical Conductor | On a conductor of arbitrary shape, the surface charge density σ is greatest at points where the radius of |
| | curvature is smallest. |
| 8. Dielectric Breakdown | The amount of charge that can be placed on a conductor is |
| | limited by the fact that molecules of the surrounding |
| | medium undergo dielectric breakdown at very high |
| | electric fields, causing the medium to become a conductor. |
| Dielectric strength | The dielectric strength is the magnitude of the electric |
| | field at which dielectric breakdown occurs. The dielectric |
| | strength of dry air is |
| | $E_{max} \approx 3 \times 10^6 \text{ V/m} = 3 \text{ MV/m}$ |
| 9. Electrostatic Potential Energy | The electrostatic potential energy of a system of point |
| | charges is the work needed to bring the charges from an |
| | infinite separation to their final positions. |
| Of point charges | $U = \frac{1}{2} \sum_{i=1}^{n} q_i V_i$ |
| Of a conductor with charge Q and | $U = \frac{1}{2}QV$ |
| potential V | |
| Of a system of conductors | $U = \frac{1}{2} \sum_{i=1}^{n} Q_i V_i$ |
| | |

| | 1. Capacitance is an important defined quantity that |
|------------------------------------|--|
| | relates charge to potential difference. |
| | 2. Two devices connected in <i>parallel</i> share a common |
| | potential difference across each device due solely to the |
| | way they are connected. |
| | 3. Two devices connected in <i>series</i> are connected by a |
| | conducting path that contains no junctions. |
| | 4. The changes in potential around any closed path <i>always</i> |
| | sum to zero. This is known as Kirchhoff's loop rule. |
| ТОРІС | RELEVANT EQUATIONS AND REMARKS |
| 1. Capacitor | A capacitor is a device for storing charge and energy. It |
| | consists of two conductors that are insulated from each |
| | other and carry equal and opposite charges. |
| 2. * Capacitance | $C \equiv \frac{Q}{V}$ |
| Single conductor | Q is the conductor's total charge, V is the conductor's |
| | potential relative to its surroundings. |
| Capacitor | Q is the magnitude of the charge on either conductor, is |
| | the magnitude of the potential difference between the |
| | conductors. |
| Of an isolated spherical conductor | $C = 4\pi \epsilon_0 R$ |
| * Of a parallel-plate capacitor | $C = \frac{\epsilon_0 A}{d}$ |
| * Energy stored in a capacitor | $U = \frac{1}{2}QV = \frac{1}{2}\frac{Q^2}{C} = \frac{1}{2}CV^2$ |

CAPACITANCE

| ΤΟΡΙΟ | RELEVANT EQUATIONS AND REMARKS |
|---------------------------|---|
| 3. Equivalent Capacitance | |
| * Parallel capacitors | When devices are connected in parallel, the voltage drop |
| | is the same across each. |
| | $C_{eq} = C_1 + C_2 + C_3 + \dots = \sum_{i=1}^n C_i$ |
| * Series capacitors | When capacitors are in series, the voltage drops add. If the |
| | total charge on each connected pair of plates is zero, then: |
| | $\frac{1}{C_{eq}} = \frac{1}{C_1} + \frac{1}{C_2} + \frac{1}{C_3} + \dots = \sum_{i=1}^n \frac{1}{C_i}$ |
| 4. Dielectrics | |
| Macroscopic behavior | A nonconducting material is called a dielectric. When a |
| | dielectric is inserted between the plates of a charged, |
| | electrically isolated capacitor, the electric field between |
| | the plates is weakened and the capacitance is thereby |
| | increased by the factor κ , which is the dielectric constant. |
| Microscopic view | The electric field in the dielectric of a capacitor is |
| | weakened because the molecular dipole moments (either |
| | preexisting or induced) tend to align with the applied field |
| | and thereby produce a second electric field inside the |
| | dielectric that opposes the applied field. The aligned |
| | dipole moment of the dielectric is proportional to the |
| | applied field. |

CAPACITANCE

| ТОРІС | RELEVANT EQUATIONS AND REMARKS |
|-------------------------|------------------------------------|
| Electric field inside | $E = \frac{E_0}{\kappa}$ |
| * Effect on capacitance | $C = \kappa C_0$ |
| Permittivity e | $\epsilon = \kappa \epsilon_0$ |
| Uses of a dielectric | 1. Increases capacitance |
| | 2. Increases dielectric strength |
| | 3. Physically separates conductors |

| | 1. Ohm's law is an empirical law that holds only for |
|-----------------------------------|--|
| | certain materials. |
| | 2. Current, resistance, and emf are important <i>defined</i> |
| | quantities. |
| | 3. Kirchhoff's rules follow from the conservation of |
| | charge and the conservative nature of the electric field. |
| TOPIC | RELEVANT EQUATIONS AND REMARKS |
| 1. * Electric Current | Electric current is the rate of flow of electric charge |
| | through a cross-sectional area. |
| | $I \equiv \lim_{\Delta t \to 0} \frac{\Delta Q}{\Delta t} = \frac{dQ}{dt}$ |
| * Drift velocity | In a conducting wire, electric current is the result of the |
| | slow drift of charge carriers that are accelerated by an |
| | electric field in the wire and then collide with the lattice |
| | ions. Typical drift speeds of electrons in wires are of the |
| | order of a few millimeters per second. For mobile charges |
| | moving in the positive direction, |
| | $I = nqv_dA$ |
| | where q is the charge per carrier, n is the charge carrier |
| | volume density, v_d is the drift velocity, and A is the cross- |
| | sectional area of the wire. |
| Current Density | The current density $ ec{J} $ is related to the drift velocity by |
| | $\vec{J} = nq \vec{v}_d$ |
| | The current <i>I</i> through a cross-sectional surface is the flux |
| | of the current density through the surface. |
| * \vec{E} in terms of \vec{J} | $\vec{E} = \rho \vec{J}$ |
| | where ρ is the resistivity of the material. |

| TOPIC | RELEVANT EQUATIONS AND REMARKS |
|---------------------------------------|---|
| 2. Resistance | |
| Definition of resistance | $R \equiv \frac{V}{I}$ |
| * In terms of resistivity | $R = \frac{\rho L}{A}$ |
| Temperature dependence of resistivity | $\rho = \rho_0 [1 + \alpha (T - T_0)]$ |
| | where α is the material's temperature coefficient, and ρ_0 is |
| | the resistivity of the material at the reference temperature |
| | T_0 , typically 20°C. |
| 3. * Ohm's Law | For ohmic materials, the resistance does not depend on |
| | either the current or the potential drop: |
| | V = IR (<i>R</i> constant) |
| 4. Power | |
| Supplied to a device or segment | P = IV |
| Delivered to a resistor | $P = IV = I^2 R = \frac{V^2}{R}$ |
| 5. Emf | |
| Source of emf | A device that supplies electrical energy to a circuit. |
| Power supplied by ideal emf source | $P = I\mathcal{E}$ |

| TOPIC | RELEVANT EQUATIONS AND REMARKS |
|--------------------------|---|
| 6. Battery | |
| Ideal | An ideal battery is a source of emf that maintains a |
| | constant potential difference between its two terminals, |
| | independent of the current through the battery. |
| Real | A real battery can be considered as an ideal battery in |
| | series with a small resistance, called its internal resistance. |
| Terminal voltage | The actual potential difference provided between the |
| | terminals of a real battery depends on the current through |
| | the battery: |
| | $\Delta V = V_b - V_a = \mathcal{E} - IR$ |
| | where in the battery the positive direction is the direction |
| | of increasing potential. |
| Total energy stored | $E_{stored} = Q\mathcal{E}$ |
| 7. Equivalent Resistance | |
| Resistors in series | $R_{eq} = R_1 + R_2 + R_3 + \dots = \sum_{i=1}^n R_i$ |
| Resistors in parallel | $\frac{1}{R_{eq}} = \frac{1}{R_1} + \frac{1}{R_2} + \frac{1}{R_3} + \dots = \sum_{i=1}^n \frac{1}{R_i}$ |
| 8. Kirchhoff's Rules | 1. When any closed loop is traversed, the algebraic sum of |
| | the changes in potential around the loop must equal |
| | zero. |
| | 2. At any junction (branch point) in a circuit where the |
| | current can divide, the sum of the currents into the |
| | junction must equal the sum of the currents out of the |
| | junction. |

| ТОРІС | RELEVANT EQUATIONS AND REMARKS |
|----------------------------|---|
| 9. Discharging a Capacitor | |
| Charge on the capacitor | $q(t) = Q_0 e^{-t/RC} = Q_0 e^{-t/\tau}$ |
| Current in the circuit | $I(t) = \frac{dQ}{dt} = \frac{V_0}{R}e^{-t/RC} = I_0 e^{-t/\tau}$ |
| Time constant | $\tau = RC$ |
| 10. Charging a Capacitor | |
| Charge on the capacitor | $q(t) = C \mathcal{E} [1 - e^{-t/RC}] = Q (1 - e^{-t/\tau})$ |
| Current in the circuit | $I(t) = \frac{\mathcal{E}}{R} e^{-t/RC} = I_0 e^{-t/\tau}$ |

TOPIC

- The magnetic field describes the condition in space in which moving charges experience a force perpendicular to their velocity.
- The magnetic force is part of the electromagnetic interaction, one of the three known fundamental interactions in nature.
- 3. The magnitude and direction of a magnetic field \vec{B} are defined by the formula $\vec{F} = q\vec{v} \times \vec{B}$, where \vec{F} is the force exerted on a particle with charge *q* moving with velocity \vec{v} .

RELEVANT EQUATIONS AND REMARKS

| 1. Magnetic Force | |
|----------------------------|---|
| * On a moving charge | $\vec{F} = q\vec{v} \times \vec{B},$ |
| * On a current element | $d\vec{F} = Id\vec{s} \times \vec{B}$ |
| Between two parallel wires | $\frac{F}{\ell} = \frac{\mu_0 I_1 I_2}{2\pi r}$ |
| | This force is attractive if the currents are in the same |
| | direction and repulsive if they are in opposite directions. |
| Unit of the magnetic field | The SI unit of magnetic fields is the tesla (T): |
| | $1 \text{ T} = 1 \text{ N/A} \cdot \text{m}$ |
| | A commonly used non-SI unit is the gauss (G), which is |
| | related to the tesla through the conversion: |
| | $1 \text{ T} = 10^4 \text{ G}$ |

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THE MAGNETIC FIELD

| ТОРІС | RELEVANT EQUATIONS AND REMARKS |
|---------------------------------------|--|
| 2. Motion of Point Charges | A particle of mass m and charge q moving with speed v in |
| | a plane perpendicular to a uniform magnetic field moves |
| | in a circular orbit. The period and frequency of the |
| | circular motion are independent of the radius of the orbit |
| | and of the speed of the particle. |
| Newton's second law | $qvB = m\frac{v^2}{r}$ |
| Cyclotron period | $T = \frac{2\pi m}{qB}$ |
| Cyclotron frequency | $f = \frac{1}{T} = \frac{qB}{2\pi m}$ |
| Velocity selector | A velocity selector consists of crossed electric and |
| | magnetic fields so that the electric and magnetic forces |
| | balance for a particle moving with speed <i>v</i> . |
| | $v = \frac{E}{B}$ |
| Mass spectrometer | The mass-to-charge ratio of an ion of known speed can be |
| | determined by measuring the radius of the circular path |
| | taken by the ion in a known magnetic field. |
| 3. Current Loops | |
| Magnetic dipole moment | $\vec{\mu} = NIA \hat{n}$ |
| Torque | $\vec{\tau} = \vec{\mu} \times \vec{B}$ |
| Potential energy of a magnetic dipole | $U = -\vec{\mu} \cdot \vec{B}$ |
| Net force | The net force on a current loop in a <i>uniform</i> magnetic field |
| | is zero. |

- 1. Magnetic fields arise from moving charges, and therefore from currents.
- 2. The Biot–Savart law describes the magnetic field produced by a current element.
- 3. Ampère's law relates the line integral of the magnetic field along some closed curve to the current that passes through any surface bounded by the curve.

TOPIC

RELEVANT EQUATIONS AND REMARKS

| . Magnetic Field \vec{B} | |
|--------------------------------|--|
| * Biot-Savart law | $d\vec{B} = \frac{\mu_0}{4\pi} \frac{Id\vec{s}\times\hat{r}}{r^2}$ |
| | where \hat{r} is a unit vector that points to the field point <i>P</i> |
| | from the current element $d\vec{s}$, and μ_0 is a constant of |
| | proportionality called the permeability of free space: |
| | $\mu_0 = 4\pi \times 10^{-7} \mathrm{T} \cdot \mathrm{m/A}$ |
| Due to a straight wire segment | $B = \frac{\mu_0}{4\pi} \frac{I}{r} (\sin \theta_1 - \sin \theta_2)$ |
| | where r is the perpendicular distance to the wire and $	heta_1$ |
| | and θ_2 are the angles subtended at the field point by the |
| | ends of the wire. |
| Due to a long straight wire | Using the above equation with $\theta_1 = 90^\circ$ and $\theta_2 = -90^\circ$, |
| | $B = \frac{\mu_0 I}{2 \pi r}$ |
| | The direction of $ec{B}$ is such that the magnetic field lines |
| | encircle the wire in the direction of the fingers of the right |
| | hand if the thumb points in the direction of the current. |
| * Inside a long solenoid | $B = \frac{\mu_0 N I}{L} = \mu_0 n I$ |
| | where n is the number of turns per unit length. |

SOURCES OF THE MAGNETIC FIELD

| ТОРІС | RELEVANT EQUATIONS AND REMARKS |
|------------------------------|---|
| 2. Magnetic Field Lines | Magnetic lines neither begin nor end. Either they form |
| | closed loops or they continue indefinitely. |
| 3. Gauss's Law for Magnetism | $\Phi_{B,net} = \oint_{surface} \vec{B} \cdot d\vec{A} = 0$ |
| 4. Magnetic Poles | Magnetic poles always occur in north–south pairs. Isolated |
| | magnetic poles have not been found. |
| 5. * Ampère's Law | $\oint_C \vec{B} \cdot d\vec{s} = \mu_0 I$ |
| | where C is any closed path and I is the current enclosed by |
| | the path. |
| Validity of Ampère's law | Ampère's law is valid only if the currents are steady and |
| | continuous. It can be used to derive expressions for the |
| | magnetic field for situations with a high degree of |
| | symmetry, such as a long, straight, current-carrying wire |
| | or a long, tightly wound solenoid. |

- 1. Faraday's law and Lenz's law are fundamental laws of physics.
- 2. Self-inductance is a property of a circuit element that relates the flux through the element to the current.

RELEVANT EQUATIONS AND REMARKS

| 1. Magnetic Flux | |
|-------------------------|---|
| * General definition | $\Phi_{B} = \int_{\text{surface}} \vec{B} \cdot d\vec{A}$ |
| Flat surface bounded by | $\Phi_{B} = NBA\cos\theta$ |
| <i>N</i> turns of wire | where <i>A</i> is the are of the surface bounded by a single turn. |
| Unit | $1 \text{ Wb} = 1 \text{ T} \cdot \text{m}^2$ |
| 2. * Faraday's Law | $\mathcal{E} = -\frac{d \Phi_{\scriptscriptstyle B}}{dt} = -\frac{d}{dt} (NBA\cos\theta)$ |
| General form | $\oint \vec{E} \cdot d\vec{s} = -\frac{d\Phi_B}{dt}$ |
| 3. Lenz's Law | The induced emf and induced current are in such a |
| | direction as to oppose, or tend to oppose, the change that produces them. |
| Alternative statement | When a magnetic flux through a surface changes, the |
| | magnetic field due to any induced current produces a flux |
| | of its own—through the same surface and opposite in sign |
| | to the original change in flux. |
| 4. Inductance | |
| Self inductance | $L = \frac{\Phi_B}{I}$ |
| Mutual inductance | $M = \frac{\Phi_{B21}}{I_1} = \frac{\Phi_{B12}}{I_2}$ |
| Unit | 1 H = 1 Wb/A |

TOPIC

MAGNETIC INDUCTION

| ΤΟΡΙΟ | RELEVANT EQUATIONS AND REMARKS |
|---|--|
| 5. EMF | |
| * Faraday's law | $\mathcal{E} = -\frac{d\Phi_B}{dt}$ |
| Motional emf | $\mathcal{E} = -B\ell v$ |
| * Self inductance (back emf) | $\mathcal{E} = -L\frac{dI}{dt}$ |
| 6. Magnetic Energy | |
| * Energy stored in an inductor | $U = \frac{1}{2}LI^2$ |
| 7. RL Circuits | |
| Potential difference across an inductor | $\Delta V = \mathcal{E} - Ir = -L\frac{dI}{dt} - Ir$ |
| | where r is the internal resistance of the inductor. For an ideal inductor $r = 0$. |
| Energizing an inductor | In a single-loop circuit consisting of a resistor that has a resistance <i>R</i> , an inductor that has a self-inductance <i>L</i> , and a battery that has an emf \mathcal{E} , the current does not reach its maximum value instantaneously, but rather takes some time to build up. If the current is initially zero, its value at some later time is given by $I(t) = \frac{\mathcal{E}}{R} (1 - e^{-Rt/L}) = I_{max} (1 - e^{-t/\tau})$ |
| Time constant | $\tau = \frac{L}{R}$ |

MAGNETIC INDUCTION

TOPIC

De-energizing an inductor

RELEVANT EQUATIONS AND REMARKS

In a single-loop circuit consisting of a resistor that has a resistance R, and an inductor that has a self-inductance L, the current does not drop to zero through a resistor instantaneously, but rather takes some time to decrease. If the current is initially I_0 , its value at some later time is given by

 $I = I_0 e^{-t/\tau}$

Maxwell's equations summarize the fundamental laws of physics that govern electricity and magnetism.

TOPICRELEVANT EQUATIONS AND REMARKS

| 1. Maxwell's Displacement Current | Ampère's law can be generalized to apply to currents that |
|-----------------------------------|---|
| | are not steady (and not continuous) if the current I is |
| | replaced by $I + I_d$, where I_d is Maxwell's displacement |
| | current: |
| | $I_d = \epsilon_0 \frac{d\Phi_E}{dt}$ |
| Generalized form of Ampère's law | $\oint_{path} \vec{B} \cdot d\vec{s} = \mu_0 (I + I_d) = \mu_0 I + \mu_0 \epsilon_0 \frac{d\Phi_E}{dt}$ |
| 2. Maxwell's Equations | The laws of electricity and magnetism are summarized by |
| | Maxwell's equations. |
| * Gauss's law | $\oint_{\text{surface}} \vec{E} \cdot d\vec{A} = \frac{Q_{\text{inside}}}{\epsilon_0}$ |
| Gauss's law for magnetism | $\oint_{surface} \vec{B} \cdot d\vec{A} = 0$ |
| Faraday's law | $\oint_{path} \vec{E} \cdot d\vec{s} = -\frac{d\Phi_B}{dt}$ |
| Ampère-Maxwell law | $\oint_{path} \vec{B} \cdot d\vec{s} = \mu_0 I + \mu_0 \epsilon_0 \frac{d\Phi_E}{dt}$ |